

# Moment Magnitude–Local Magnitude Calibration for Earthquakes in Western Canada

by John Ristau, Garry C. Rogers, and John F. Cassidy

**Abstract** Local magnitude ( $M_L$ ) is the primary magnitude scale calculated for western Canada by the Geological Survey of Canada (GSC). Moment magnitude ( $M_w$ ), derived from moment tensor analysis, provides a more robust estimate of the magnitude of earthquakes but is more demanding to calculate. Moment tensor analysis of regional seismic data for earthquakes with magnitudes larger than 3.5 in western Canada is now possible owing to the installation of more than 40 three-component broadband stations in western Canada, the Pacific Northwest of the United States, and southeast Alaska. More than 100 regional moment tensor solutions have been calculated in the Canadian Cordillera and Vancouver Island/Puget Sound region for 1996–2004 at the GSC. These solutions, along with 45 prior solutions, allow the calibration of  $M_w$ – $M_L$  throughout much of western Canada. Continental crust events in the Canadian Cordillera and Vancouver Island/Puget Sound region are found to have  $M_w = M_L$  for earthquakes with  $M_L \geq 3.6$ . In contrast, earthquakes located within the subducting slab in the Vancouver Island/Puget Sound region, where there are complex source–receiver travel paths, have  $M_w$  systematically larger than  $M_L$  by nearly 0.6 magnitude units. The calibrations of  $M_w$  with  $M_L$  are an important result that will allow the western Canadian earthquake database to be used more effectively for tectonic studies and seismic hazard analysis.

## Introduction

Local magnitude ( $M_L$ ) was the first magnitude scale to be developed in an attempt to quantitatively describe the size of an earthquake. It was developed by Richter (1935) specifically for earthquakes in southern California.  $M_L$  is now widely used, often in tectonic environments that can be completely different from southern California. Therefore, it is necessary to calibrate  $M_L$  so that it gives magnitudes that are consistent with other magnitude scales such as body-wave magnitude ( $m_b$ ) or moment magnitude ( $M_w$ ).

With the recent ability to calculate regional moment tensor (RMT) solutions for earthquakes as small as  $M \sim 3.5$  in western Canada, it has become possible to build a large catalogue of  $M_w$  values for earthquakes in the Canadian Cordillera and the Vancouver Island/Puget Sound region. At the Geological Survey of Canada (GSC), 102 RMT solutions for events in this region have been calculated for 1996–2004 with  $M_w$  ranging from 3.4 to 6.8. These solutions, along with 30 RMT solutions calculated by Oregon State University (OSU) in 1994–1995 (Braunmiller and Nábělek, 2002) and 15 Harvard centroid moment tensor (CMT) solutions from 1976–1993 (Harvard CMT catalog), allow for a  $M_w/M_L$  calibration for earthquakes in the Canadian Cordillera and Vancouver Island/Puget Sound region.  $M_w$  is the preferred magnitude for seismic hazard analysis, and determining how

other magnitude scales are related to it is important, as  $M_w$  estimates are not always available. The purpose of this study was to determine how  $M_L$  relates to  $M_0$  (seismic moment) and  $M_w$  in the Canadian Cordillera and Vancouver Island/Puget Sound region. This article complements that of Ristau *et al.* (2003), which determined the  $M_w/M_L$  relationship for the offshore region of western Canada, and completes the  $M_w/M_L$  calibration for the most seismically active regions of western Canada.

## The Magnitude Scale

A brief summary of  $M_L$  and  $M_w$  are given here; Ristau *et al.* (2003) provide a more detailed description. Richter (1935) defined  $M_L$  as

$$M_L = \log A - \log A_0 \quad (1)$$

where  $A$  is the amplitude of the horizontal ground displacements of the earthquake and  $A_0$  is that of a reference event, at a distance of 100 km, as measured on a Wood–Anderson seismograph. In western Canada, the method used to calculate  $M_L$  is similar to that of Richter (1935); it uses the original  $\log A_0$  values and applies the calculations in the dis-

tance range of 50–600 km. Stations with an epicentral distance of less than 50 km are not used to calculate  $M_L$  in order to minimize the effect of focal depth. The main difference is that the maximum amplitude used for earthquakes in western Canada has been consistently calculated from the vertical component since routine magnitude calculation began in 1955, whereas Richter (1935) used the horizontal amplitudes from Wood–Anderson seismographs. There is also a period correction to adjust for the different period responses of the seismographs used in western Canada compared with a Wood–Anderson seismograph.

Magnitude estimates (e.g.,  $M_L$ ,  $m_b$ ) are limited by making frequency-dependent measurements of the amplitudes of surface or body waves, which results in magnitude saturation for larger earthquakes.  $M_w$ , first proposed by Kanamori (1977), is computed directly from  $M_o$ , which is not dependent on the frequency so long as the frequencies used are well below the corner frequency.  $M_o$  does not saturate and is a fundamental physical quantity directly related to the earthquake fault area and the average slip on the fault. It is the best representation of the size of earthquake, and  $M_w$  gives a magnitude estimate directly related to  $M_o$ . Hanks and Kanamori (1979) derived a relationship for calculating  $M_w$  with respect to  $M_o$  that is consistent with the  $M_L$ – $M_s$  (surface-wave magnitude scale) relation. It is given by

$$M_w = \frac{2}{3} \log M_o - 10.7 \quad (2)$$

where  $M_o$  is in dyne cm. Determination of  $M_o$  is much more computationally extensive than magnitude calculation; however, several program packages have been developed to make the process routine, such as the code used in this study (Ammon, 2001). Therefore, how  $M_L$  relates to  $M_o$  can be determined by finding out how  $M_L$  relates to  $M_w$ .

### Regional Moment Tensor Analysis

Since the mid-1990s more than 40 three-component broadband seismometers have been installed in western Canada, the Pacific Northwest of the United States, and southeast Alaska, and they now provide high-quality seismic data suitable for moment tensor analysis (Fig. 1). These data, along with improved methods and increased computing power, have made it possible to routinely calculate RMT solutions for smaller earthquakes in western Canada, that is,  $M_w \geq \sim 3.5$ . Regional moment tensor solutions differ from Harvard or USGS moment tensor solutions in that they use regional data (source–receiver distances of  $\sim 1000$  km or less) and region-specific Earth models. For  $M \leq \sim 5.0$  the signal-to-noise ratio at the low frequencies used in global analysis is poor, and higher frequencies must be used. Higher frequency signals are more complicated, and the generic whole-Earth models used in global moment tensor analysis are not sufficiently detailed to accurately model the observed waveforms. Earth models specific to the source

region must be used in order to adequately model the observed data. By extending the magnitude threshold down to  $M_w \sim 3.5$ , it has been possible to calculate more than 10 times as many moment tensor solutions compared with teleseismic methods. Because of low signal-to-noise ratios at low frequencies (below the corner frequency) and the inability to properly model higher frequency signals, it is not always possible to calculate a RMT solution for earthquakes with  $M_w < 4.0$ ; therefore, the catalog for events with  $M_w < 4.0$  is not complete.

The RMT solutions presented here were calculated using the code of Ammon (2001) as developed for use on smaller magnitude earthquakes. For the majority of the events, the observed waveforms are bandpass filtered between 20 and 50 sec (0.02–0.05 Hz), which generally provides a good signal-to-noise ratio for modeling the observed waveforms (e.g., Braunmiller and Nábêlek, 2002). In this frequency range the seismograms are dominated by guided waves and surface waves, which can be adequately modeled using 1D velocity models. Harvard CMT solutions typically use waveform energy with periods greater than 45 sec (less than 0.022 Hz) (Dziewonski *et al.*, 1981), and USGS moment tensor solutions use a 15–55 sec (0.018–0.067 Hz) passband (Sipkin, 1986). Details on the moment tensor algorithm and method can be found in Ammon (2001) and Ristau (2004) and will not be discussed here.

### Moment Magnitude–Local Magnitude Calibration

This article is the first study to calibrate  $M_w$  with  $M_L$  for all of the most seismically active onshore regions of western Canada. It incorporates the results of Hyndman *et al.* (2005) for the northern Cordillera, and the work of Bolton (2003), who compared  $M_w$  with  $M_L$  for seven in-slab events in the Vancouver Island/Puget Sound region. Ristau *et al.* (2003) compared  $M_w$  with  $M_L$  for more than 260 earthquakes off the west coast of Vancouver Island and in the Queen Charlotte Islands region. The travel paths of those earthquakes contain substantial segments of oceanic lithosphere, which have very different wave transmission characteristics compared with continental crust. The essential point is that the  $L_g$  phase, which is normally used to calculate  $M_L$ , does not propagate through oceanic crust when the length of the oceanic crustal path is greater than 100–200 km owing to the effect of the thin crust on the crustal wave guide (Press and Ewing, 1952; Zhang and Lay, 1995). Therefore,  $M_w$ – $M_L$  relations for the offshore region cannot be extrapolated to the onshore regions. Ristau *et al.* (2003) contains a detailed discussion on the problems of calculating  $M_L$  for earthquakes occurring off Canada's west coast.

Nearly 150 moment tensor solutions have been calculated for the Canadian Cordillera and the Vancouver Island/Puget Sound region by the GSC, OSU, and Harvard, ranging from  $M_w$  3.4–7.5 (Fig. 2). To study the  $M_w/M_L$  relationship, all of the events occurring in the continental crust are grouped together regardless of whether they are located in

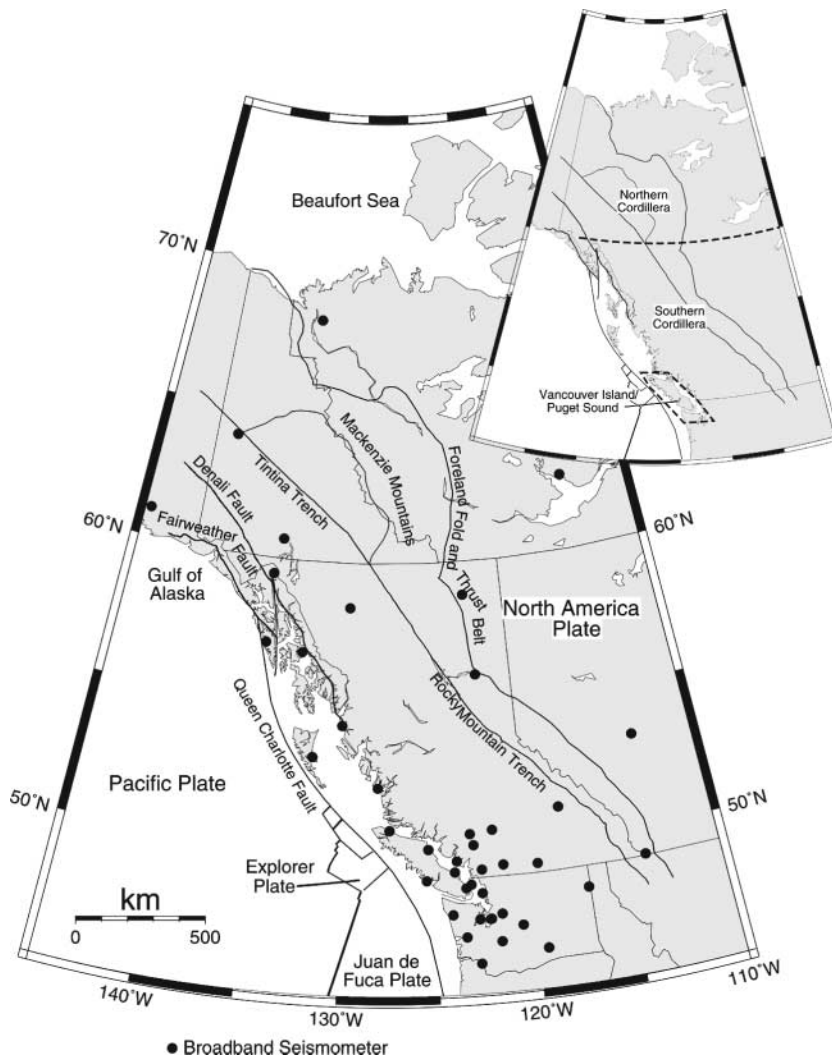


Figure 1. Locations of three-component broadband seismometers in western Canada, the Pacific Northwest of the United States, and southeast Alaska through to the beginning of 2005. These stations are routinely used to calculate RMT solutions in western Canada and adjacent regions. Also shown are the major tectonic features of western Canada. Inset: locations of the Canadian Cordillera and the Vancouver Island/Puget Sound regions.

the Canadian Cordillera or the Vancouver Island/Puget Sound region. Then, events located in just the Vancouver Island/Puget Sound region are considered to study the  $M_w/M_L$  discrepancy for events occurring within the overlying North America crust compared with those occurring within the subducting Juan de Fuca slab.

#### Continental Crust Events

A total of 131 continental crust events with  $M_w$  ranging from 3.4 to 7.5 are used to compare  $M_w$  with  $M_L$ . It has been shown that a unique moment tensor solution can often be obtained using as few as one or two three-component broadband stations (e.g., Dreger and Helmberger, 1993; Delouis and Legrand, 1999). However, inaccuracies in modeling waveforms using 1D velocity models, particularly when the source–receiver distances are several hundred kilometers, can result in nonunique and unstable solutions. Moment tensor solutions calculated using only one or two stations can depend greatly on the velocity model used to calculate the Green's functions. Solutions calculated using several sta-

tions are generally more reliable and more stable (e.g., Dreger, 2000). In this study of the Canadian Cordillera, we typically use 5–10 stations having a good azimuthal distribution with source–receiver distances that are often greater than 500 km.

Figure 3 (top) compares  $\log(M_o)$  with  $M_L$  for all events occurring within the North America plate, with the best-fit line (thin solid line) and 95% confidence limits (dashed lines) also shown. The thick black line is the Hanks and Kanamori (1979) relationship (equation 2), solved for  $M_o$  and replacing  $M_w$  with  $M_L$ , which represents a 1:1 relationship between  $M_w$  and  $M_L$ . The Hanks and Kanamori (1979) relationship falls outside of the 95% confidence limits for most of the data set, suggesting that  $M_w$  and  $M_L$  are not consistent when using the entire data set. In Figure 3 (top), events with  $M_L \sim 3\text{--}4$  have  $M_o$  values consistently on the high side of the Hanks and Kanamori (1979) line. Continental crust earthquakes with  $M_L \leq \sim 3.5$  are at the lower magnitude limit for being able to calculate RMT solutions and generally have a worse fit between the synthetic and observed waveforms than events with  $M_L > 3.5$ . Therefore, the

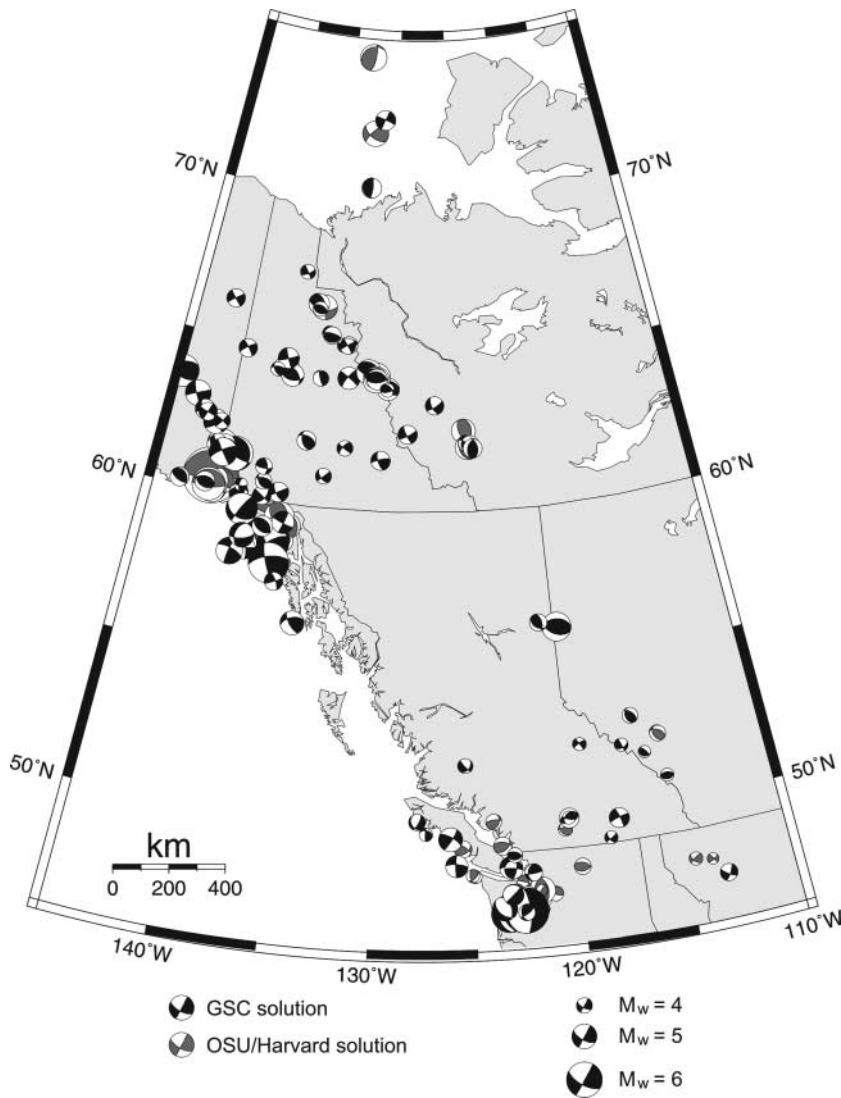


Figure 2. Moment tensor solutions in the Canadian Cordillera and Vancouver Island/Puget Sound region calculated by the GSC, OSU, and Harvard shown as lower hemisphere fault mechanisms.

$M_o$  values may not be reliable. To determine the lowest  $M_L$  at which  $M_L$  and  $M_o$  are consistent with the Hanks and Kanamori (1979) relationship, the data set is cut off at varying  $M_L$  levels. Figure 3 (middle) and (bottom) show the results using a minimum  $M_L$  of 3.4 and 3.6 respectively. For  $M_L \geq 3.6$ , there is excellent agreement at the 95% confidence limits between the data presented in this study and the Hanks and Kanamori (1979) relation.

#### Overlying Crust Versus Subducting Slab

There are 38 events available for the Vancouver Island/Puget Sound region—23 located in the overlying crust of the North America plate, 13 in the subducting slab of the Juan de Fuca plate, and two that may be either overlying crust or subducting slab events. Figure 4 (top left) compares  $M_w$  with  $M_L$  for all available events in the Vancouver Island/Puget Sound region regardless of magnitude, using the method of Ristau *et al.* (2003). The results do not vary significantly whether the uncertain events are considered as

overlying crust or subducting slab events; therefore, we have considered those events as in-slab events. The dashed line represents an ideal 1:1 relationship between  $M_w$  and  $M_L$ , and the solid line is a best-fit line assuming a slope parallel to the 1:1 line. The offset is calculated by taking an average of the residuals between  $M_w$  and the 1:1 line, and the standard deviation of the residuals is used as the error. The overlying crust events are mainly smaller magnitude events and have  $M_w$   $0.12 \pm 0.29$  magnitude units larger than  $M_L$ .

There is no method to quantitatively calculate the uncertainty on the seismic moment by way of moment tensor solutions. Ekström and England (1989) estimated an error in the seismic moment for Harvard CMT solutions by comparison of CMT results with moment estimates from geodetic and other seismic data. They estimated an error of 20% for the moment, which corresponds to a factor of 1.4 uncertainty at the 95% confidence level. In a tectonically complex region such as the Vancouver Island/Puget Sound region, it is difficult to accurately model the observed waveforms using a 1D Earth model. Therefore, we use a conservative estimate

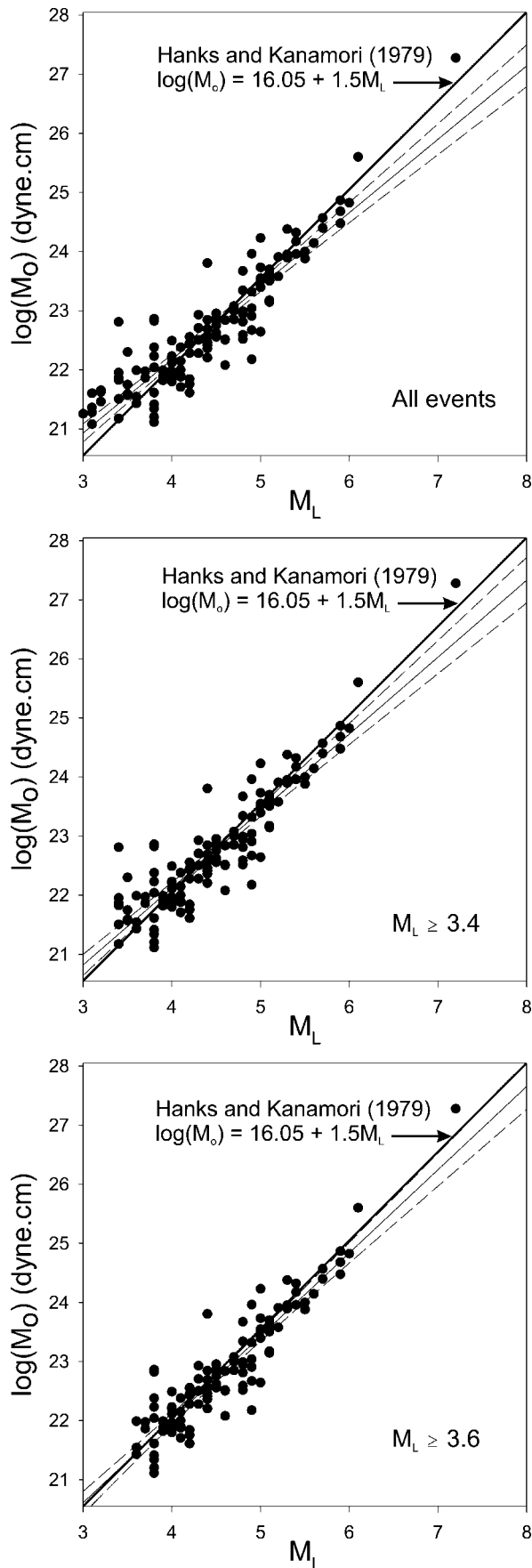


Figure 3.  $M_o/M_L$  relationship for continental crust earthquakes in the Canadian Cordillera and Vancouver Island/Puget Sound regions. The thin solid line is a best-fit line between  $\log(M_o)$  and  $M_L$ , and the dashed lines are 95% confidence limits. The thick solid line is the Hanks and Kanamori (1979) relation with  $M_L$  in place of  $M_w$ . (Top) All continental crust events; (middle) events with  $M_L \geq 3.4$ ; (bottom) events with  $M_L \geq 3.6$ . When  $M_L$  is  $\geq 3.6$  the Hanks and Kanamori (1979) relation falls within the 95% confidence limits, which shows that  $M_w$  and  $M_L$  have a 1:1 relationship for  $M_L \geq 3.6$ .

on the uncertainty in the seismic moment of a factor of 2, which corresponds to approximately a 0.2 uncertainty in magnitude. Considering a  $M_w$  uncertainty of 0.2, the  $M_w/M_L$  discrepancy for events occurring in the overlying crust is likely not significant statistically. Similar to the data set in Figure 3, events with  $M_L \leq 3.5$  in Figure 4 (top left) have  $M_w$  values consistently higher than  $M_L$ . When comparing only overlying crust events with  $M_L \geq 3.6$  as in Figure 3 (bottom),  $M_w$  and  $M_L$  are equivalent (Fig. 4, top right).

The in-slab data set (Fig. 4, bottom) is small but with a wide range of magnitudes. The subducting slab events have  $M_w$  almost 0.6 magnitude units larger than  $M_L$ , which is significant even considering a factor of 2 uncertainty in calculating  $M_o$ . The 0.6 magnitude discrepancy is observed regardless of whether the entire data set is used (Fig. 4, bottom left) or only events with  $M_L \geq 3.6$  (Fig. 4, bottom right), demonstrating that in-slab events need to be considered separately from overlying crust events. The larger discrepancy between  $M_w$  and  $M_L$  for in-slab events is likely related to the more complex source–receiver travel path, which can have a significant effect on  $M_L$  estimates.

Discussion and Conclusions

We have determined that, on average,  $M_w$  is equivalent to  $M_L$  with an uncertainty of about 0.2 magnitude units for earthquakes with  $M_L \geq 3.6$  occurring in the continental crust of the Canadian Cordillera and the Vancouver Island/Puget Sound region. Earthquakes with  $M_L$  of  $\sim 3.6$  are at about the lower limit for being able to calculate RMT solutions, and  $M_o$  values for smaller earthquakes may not be reliable. The 1:1 relationship between  $M_w$  and  $M_L$  also holds when considering overlying crust events located only in the Vancouver Island/Puget Sound region. Events located in the subducting slab in the Vancouver Island/Puget Sound region have  $M_w$  nearly 0.6 magnitude units larger than  $M_L$ . This is a critical new result, as large, damaging earthquakes can occur within the subducting slab and accurate magnitude and, particularly, seismic moment estimates are important for seismic hazard analyses and tectonic studies (e.g., Mazzotti *et al.*, 2002; Hyndman *et al.*, 2003). The magnitude relationship between crustal and slab events is an issue that can be addressed in future studies using more detailed Earth

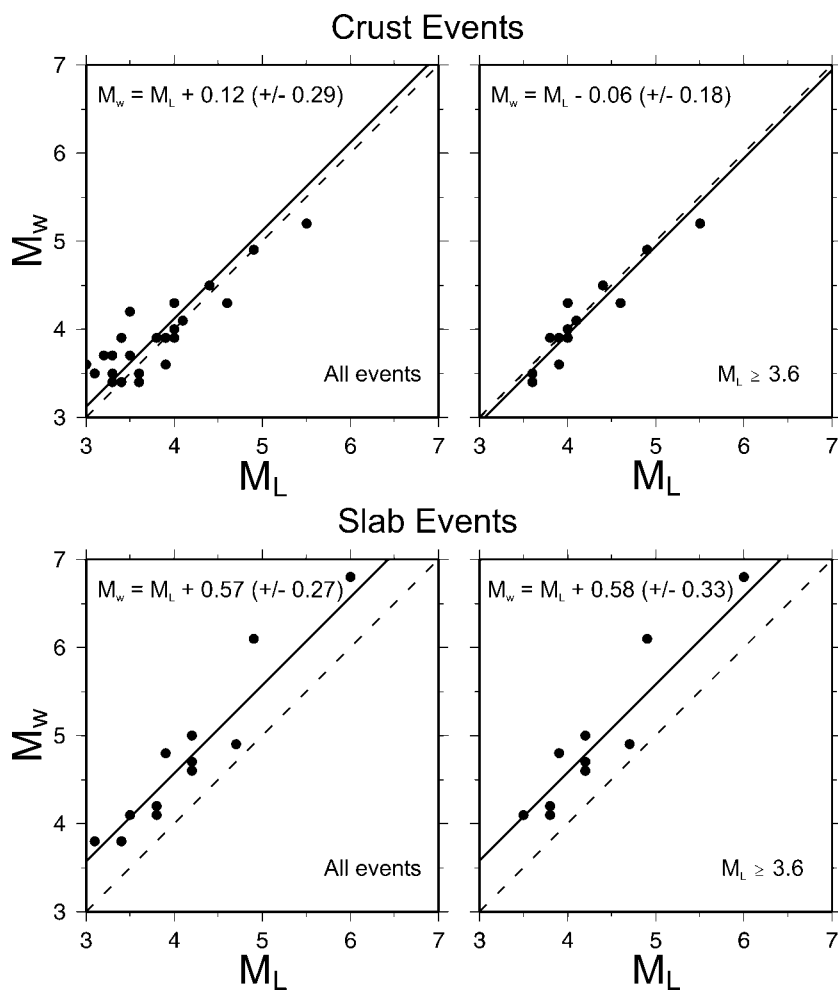


Figure 4.  $M_w/M_L$  comparison for events in the Vancouver Island/Puget Sound region. In each case the dashed line represents a 1:1 relationship between  $M_w$  and  $M_L$  and the solid line is a best-fit line assuming a slope parallel to the 1:1 line. The  $M_L$  correction is indicated for each region. (Top) Earthquakes occurring within the overlying crust; (bottom) earthquakes located within the subducting slab.

models and carefully examining the effect of the subducting slab and overlying crust on modeled waveforms. Establishing that  $M_w$  and  $M_L$  have a 1:1 relationship for continental crust events in the Canadian Cordillera and Vancouver Island/Puget Sound region is important as  $M_L$  is the primary magnitude calculated by the GSC for earthquakes in western Canada and has been calculated in a similar manner since 1955.  $M_L$  values in the western Canadian earthquake database can now be converted to  $M_w$  and  $M_o$ , which can then be used for seismic hazard analysis and tectonic studies. This study completes the  $M_w/M_L$  calibration for the seismically active onshore and offshore regions of western Canada.

#### Acknowledgments

We would like to thank Chuck Ammon for providing the moment tensor code and for a great deal of valuable advice and suggestions on calculating regional moment tensor solutions. John Adams and an anonymous reviewer provided valuable comments that helped improve this manuscript. Many of the figures were created using GMT (Wessel and Smith, 1991). Regional moment tensor solutions for western Canada are available at [www.pgc.nrcan.gc.ca/seismo/MTS](http://www.pgc.nrcan.gc.ca/seismo/MTS).

#### References

- Ammon, C. J. (2001). Moment-tensor inversion overview, <http://eqseis.geosc.psu.edu/~cammon/>, last modified 6 December 2004 (last accessed January 2005).
- Bolton, M. K. (2003). Juan de Fuca plate seismicity at the northern end of the Cascadia subduction zone, *M.Sc. Thesis*, University of Victoria, Victoria, Canada, 238 pp.
- Braunmiller, J., and J. Nábělek (2002). Seismotectonics of the Explorer region, *J. Geophys. Res.* **107**, no. B10, 2208, doi: 10.1029/2001JB000200.
- Delouis, B., and D. Legrand (1999). Focal mechanism determination and identification of the fault plane of earthquakes using only one or two near-source seismic recordings, *Bull. Seism. Soc. Am.* **89**, 1558–1574.
- Dreger, D. S. (2000). *Berkeley Automatic Seismic Moment Tensor Code*, Release 1.0, 16 pp.
- Dreger, D. S., and D. V. Helmberger (1993). Determination of source parameters at regional distances with three-component sparse network data, *J. Geophys. Res.* **98**, 8107–8125.
- Dziewonski, A. M., T.-A. Chou, and J. H. Woodhouse (1981). Determination of earthquake source parameters from waveform data for studies of global and regional seismicity, *J. Geophys. Res.* **86**, 2825–2852.
- Ekström, G., and P. England (1989). Seismic strain rates in regions of distributed continental deformation, *J. Geophys. Res.* **94**, 10,231–10,257.

- Hanks, T. C., and H. Kanamori (1979). A moment magnitude scale, *J. Geophys. Res.* **84**, 2348–2350.
- Harvard Centroid Moment Tensor Catalog, [www.seismology.harvard.edu/CMTsearch.html](http://www.seismology.harvard.edu/CMTsearch.html) (last accessed January 2005).
- Hutton, L. K., and D. M. Boore (1987). The  $M_L$  scale in southern California, *Bull. Seism. Soc. Am.* **77**, 2074–2094.
- Hyndman, R. D., S. Mazzotti, D. Weichert, and G. C. Rogers (2003). Frequency of large crustal earthquakes in Puget Sound–Southern Georgia Strait predicted from geodetic and geological deformation rates, *J. Geophys. Res.* **108**, no. B1, 2033, doi: 10.1029/2001JB001710.
- Hyndman, R. D., P. Flück, S. Mazzotti, T. Lewis, J. Ristau, and L. Leonard (2005). Current tectonics of the northern Canadian Cordillera, *Can. J. Earth Sci.* **42** (in press).
- Kanamori, H. (1977). The energy release in great earthquakes, *J. Geophys. Res.* **82**, 2981–2987.
- Mazzotti, S., H. Dragert, R. D. Hyndman, M. M. Miller, and J. A. Henton (2002). GPS deformation in a region of high crustal seismicity: N. Cascadia forearc, *Earth Planet. Sci. Lett.* **98**, 41–48.
- Press, F., and M. Ewing (1952). Two slow surface waves across North America, *Bull. Seism. Soc. Am.* **42**, 219–228.
- Richter, C. F. (1935). An instrumental earthquake magnitude scale, *Bull. Seism. Soc. Am.* **25**, 1–32.
- Ristau, J. P. (2004). Seismotectonics of western Canada from regional moment tensor analysis, *Ph.D. Thesis*, University of Victoria, Victoria, Canada, 209 pp.
- Ristau, J., G. C. Rogers, and J. F. Cassidy (2003). Moment magnitude–local magnitude calibration for earthquakes off Canada’s west coast, *Bull. Seism. Soc. Am.* **93**, 2296–2300.
- Sipkin, S. A. (1986). Estimation of earthquake source parameters by the inversion of waveform data: global seismicity, *Bull. Seism. Soc. Am.* **25**, 1515–1541.
- Wessel, P., and W. H. F. Smith (1991). Free software helps map and display data, *EOS* **72**, 441.
- Zhang, T.-R., and T. Lay (1995). Why the  $L_g$  phase does not traverse oceanic crust, *Bull. Seism. Soc. Am.* **85**, 1665–1678.

Geological Survey of Canada  
Pacific Geoscience Centre  
P.O. Box 6000  
Sidney, British Columbia V8L 4B2  
Canada

School of Earth and Ocean Sciences  
University of Victoria  
Victoria, British Columbia V8L 3P6  
Canada  
jristau@nrcan.gc.ca  
grogers@nrcan.gc.ca  
jcassidy@nrcan.gc.ca

Manuscript received 17 February 2005.